
Travel Speed Forecasting using Continuous Conditional Random Fields

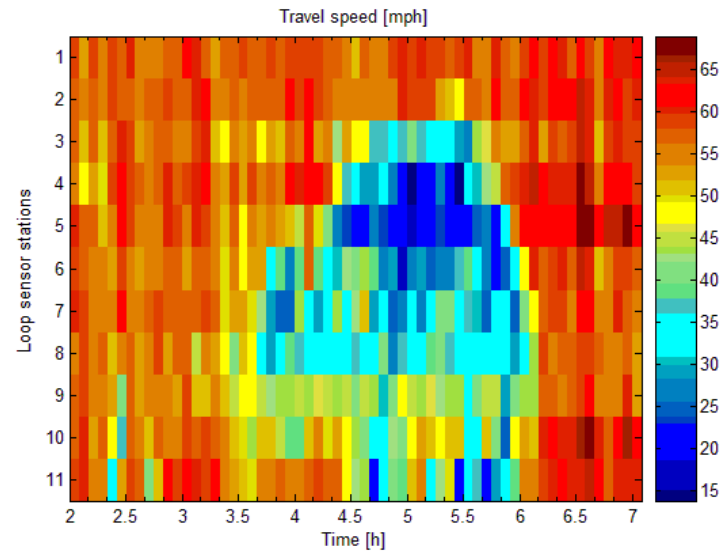
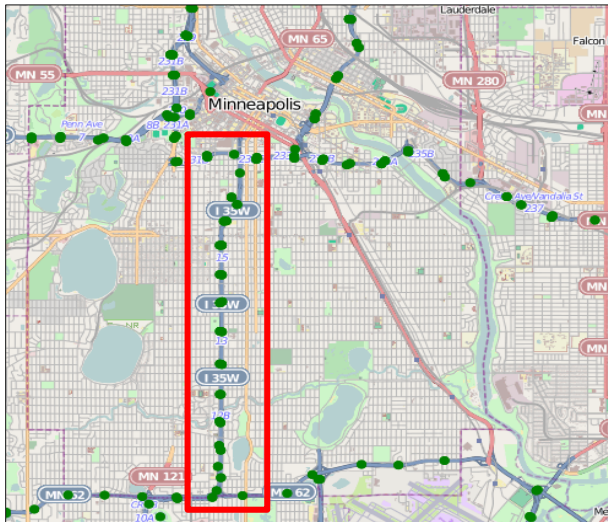
Djuric, Radosavljevic, Coric, Vucetic

Issues in travel speed forecast

- Many proposed predictors
 - How to integrate them?
 - Inherent correlations between variables
 - Speeds at neighboring road sections
 - Speeds at neighboring time intervals
 - Missing data issue
 - Sensor failures
 - Might pose a serious problem
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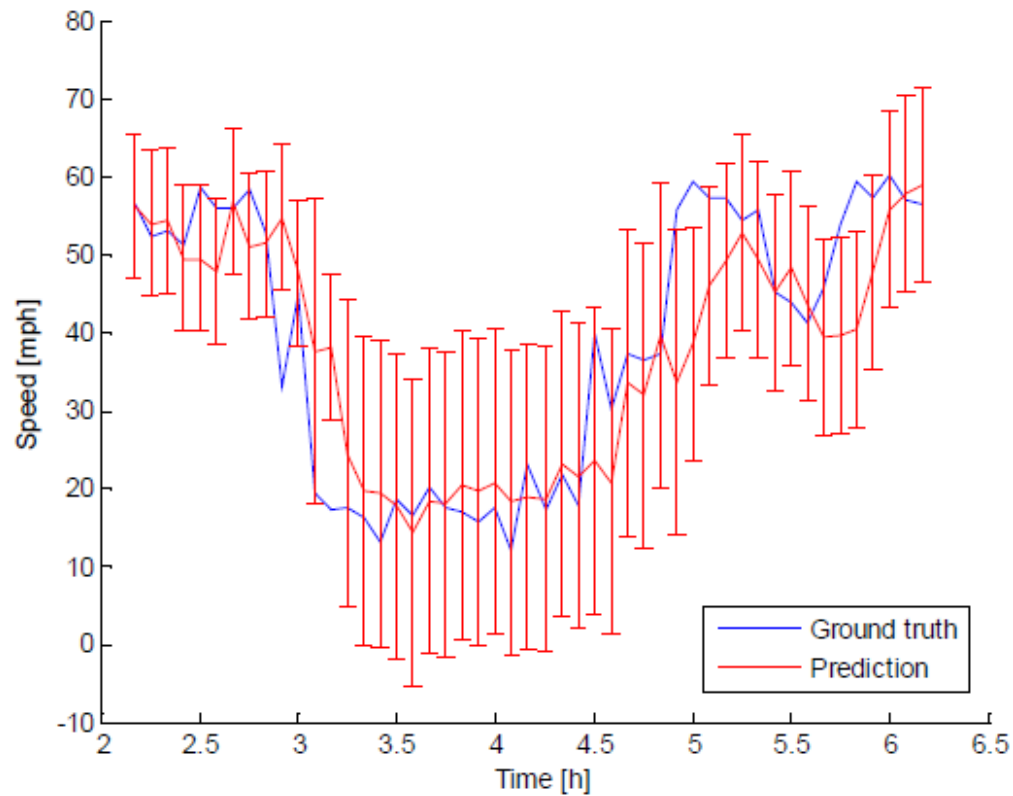
Problem setting

- Predict travel speeds on I-35W highway, Minneapolis, MN, from April to July, 2003
- Up to 1h ahead, in 10-min increments, across 11 consecutive sensor stations



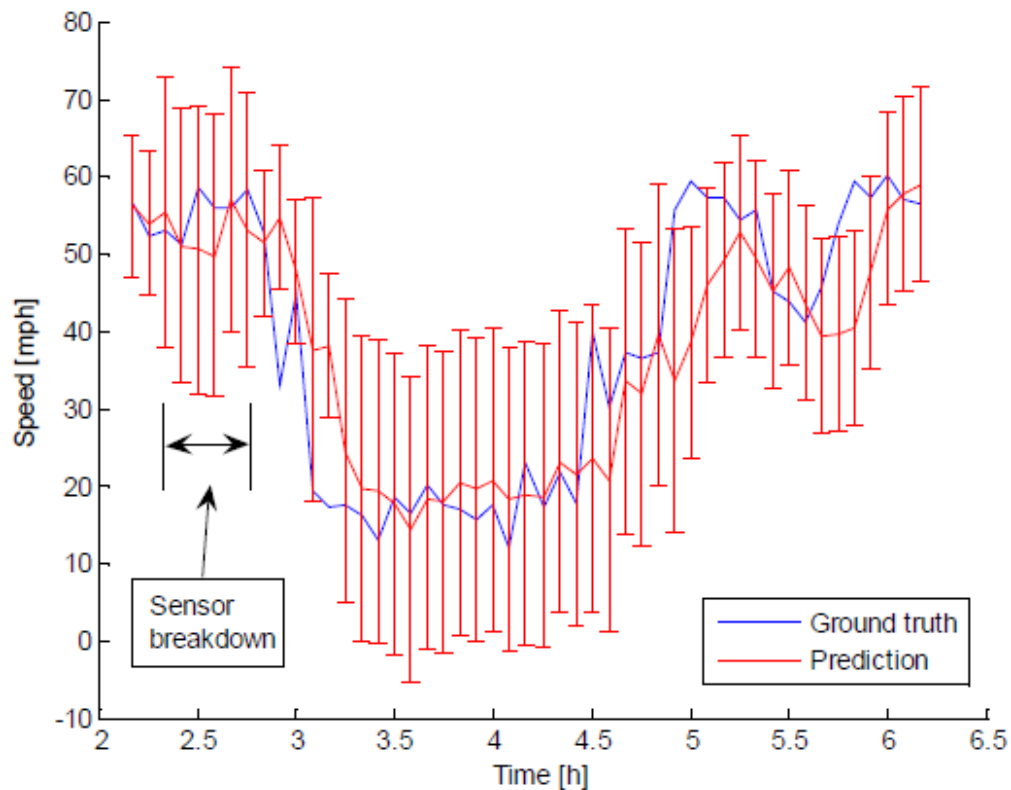
Results

- Predictions for 10-min horizon:



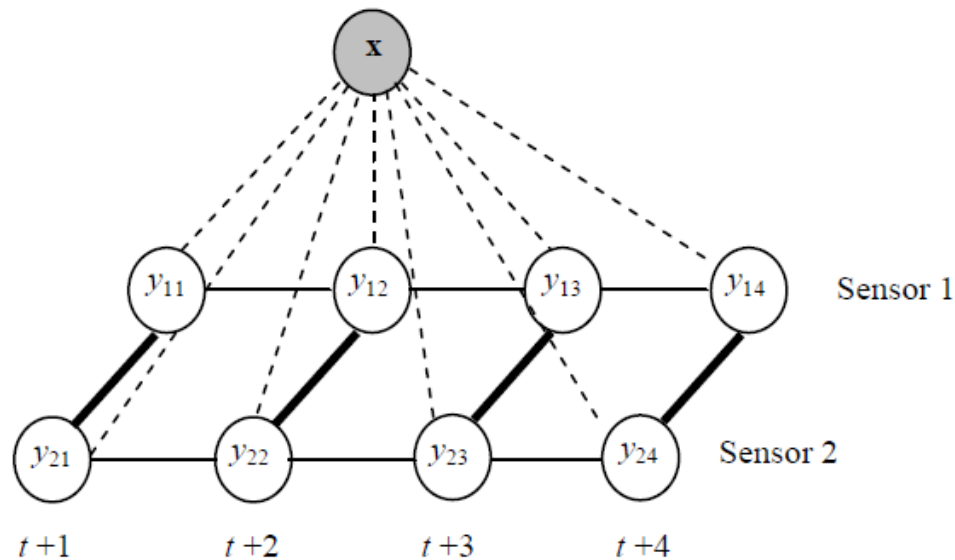
Results – Missing data

- Model still predicts, but with less confidence:



CCRF model

- Undirected graphical model
- Uses all available data \mathbf{x} (sensor readings, historical data, weather forecast, ...)
- Outputs predictions \mathbf{y} (speed, volume, occupancy, ...)



CCRF model – Cont'd

- Conditional distribution

$$P(\mathbf{y} | \mathbf{x}) = \frac{1}{Z(\mathbf{x}, \boldsymbol{\alpha}, \boldsymbol{\beta})} \exp\left(\sum_{i=1}^N A(\boldsymbol{\alpha}, y_i, \mathbf{x}) + \sum_{i \sim j} I(\boldsymbol{\beta}, y_i, y_j, \mathbf{x})\right)$$

- Association and Interaction potentials

$$A(\boldsymbol{\alpha}, y_i, \mathbf{x}) = -\sum_{m=1}^M \delta_{mi}(\mathbf{x}) \alpha_m (y_i - \theta_{mi}(\mathbf{x}))^2$$

$$I(\boldsymbol{\beta}, y_i, y_j) = -\sum_{k=1}^K w_{ij}^k \beta_k (y_i - y_j)^2$$

Conclusions

- CCRF suitable for traffic forecast
 - Inherent temporal and spatial correlations in data
 - Flexible model
 - Data from various predictors
 - New knowledge easily incorporated
 - New neighborhood definitions
 - Regime-switching
 - Robustness to sensor failures
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Visit our poster at:

Innovations in Transportation Network Modeling

Time: Tomorrow, 2:30PM- 5:00PM

Location: Hilton, Washington DC
